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# Tutorial On The Singular Value Decomposition

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# 1 SVD Theorem

Let  $A$  be a real valued  $m \times n$  matrix, where  $m \geq n$ . Then  $A$  can be decomposed as follows:

$$A = U W V^T \tag{1}$$

where  $U$  is a real valued  $m \times m$  orthonormal matrix:  $U U^T = I_m$ ,  $W$  is an  $m \times n$  matrix whose diagonal elements are non-negative real values and whose off-diagonal elements are zero, and  $V$  is a  $n \times n$  real valued orthonormal matrix;  $V V^T = I_n$ . The columns of  $U$  are called the left singular vectors. the columns of  $V$  are called the right singular vector, the diaonal elements of  $W$  are called called the *singular values*. The singular value decomposition exists always and is unique up to 1) Same permutations in columns of  $U$ ,  $W$  and  $V$ . 2) Linear combinations of columnns of  $U$  and  $V$  with equal singular values.

Note

$$A A^T = U W V^T V W^T U^T = U W W^T U^T \tag{2}$$

Thus the columnns of  $U$  are the eigenvectors of  $A A^T$  and the diagonal elements of  $W W^T$  are its eigenvalues. Moreover

$$A^T A = V W^T U^T U W V^T = V W^T W V^T \tag{3}$$

Thus the columnns of  $V$  are the eigenvectors of  $A^T A$  and the diagonals elements of  $W^T W$  its eigenvalues.

If  $X$  is a matrix  $X_{i,j}$  will represent the element in the  $i^{th}$  row,  $j^{th}$  column, and  $X_i$  will represent the  $i^{th}$  column vector. Note  $A_{i,j} = \sum_{k=1}^n w_{k,k} U_{i,k} V_{i,k}$ . Thus we can approximate  $A$  well by deleting columns of  $U$  and  $V$  with small singular values.

## 2 Properties for Square Matrices

### 2.1 Definitions

1.  $A$  be an  $n \times n$  square matrix.
2.  $N_A = \{x \in \mathbb{R}^n : Ax = 0\}$ , the **null space** of  $A$ .
3.  $\dim N_A$ , the dimensionality of the null space of  $A$ , also known as the **nullity** of  $A$ .
4.  $R_A = \{x \in \mathbb{R}^n : Ax \neq 0\}$ , the **range** of  $A$ .
5.  $\dim R_A$ , the dimensionality of the range of  $A$ , also know as **the rank** of  $A$ .  
It is well known that rank plus nullity equals  $n$ .

### 2.2 Properties

1.  $\dim R_A = \text{card}\{w_i \in \text{diag} W : w_i > 0\}$
2.  $\dim N_A = \text{card}\{w_i \in \text{diag} W : w_i = 0\}$
3. Let  $U_i$  the  $i^{th}$  column of  $U$ . Then  $\{U_i : w_i > 0\}$  is a basis of  $R_A$  and  $\{U_i : w_i = 0\}$  is a basis of  $N_A$
4. Let  $\tilde{W}$  be a diagonal matrix with

$$\tilde{w}_{i,i} = \begin{cases} \frac{1}{w_{i,i}} & \text{if } w_{i,i} > 0 \\ 0 & \text{if } w_{i,i} = 0 \end{cases} \tag{4}$$

5. If  $A$  is square (i.e.,  $m = n$ ) and all  $w_i > 0$ . Then  $A^{-1} = VW^{-1}U^T$ .

To see why simply note that  $(VW^{-1}U^T)(UWV^T) = I_n$

6. The value  $\hat{x} = V\tilde{W}U^Tb$  solves for the linear equation  $Ax = b$  in the following sense

- (a) If  $A$  is non-singular  $\hat{x}$  is the unique solution to the equation.
- (b) If  $A$  is singular and  $b \in R_A$  then  $\hat{x}$  is the solution with smallest norm.
- (c) If  $A$  is singular and  $b \in N_A$  then  $\hat{x} = \operatorname{argmin}_x |Ax - b|$

### 2.3 Rectangular matrices

1. If  $m < n$  the system  $Ax = b$  has less equations than unknowns. Patch  $A$  and  $b$  with zeroes to form an  $n \times n$  system. The solution found via SVD is minimum norm.
2. If  $m > n$  there are more equations than unknowns. The solution found via SVD is least squares.

### 2.4 Neural net interpretation

Let rows of  $A$  represent exemplars of dimensionality  $n$ . We know dropping  $n - p$  small singular values and their associated columns in  $U$  and  $V$  allows us to get an approximation to  $A$ . Let  $\hat{U}$ ,  $\hat{W}$  and  $\hat{V}$  represent “chopped” versions of the corresponding matrices, and  $\hat{A} = \hat{U}\hat{W}\hat{V}^T$ . We can retrieve the approximation to the  $i^{th}$  exemplar by premultiplying  $\hat{A}$  times a row vector with all components set to 0 except the  $i^{th}$  component which is set to 1.

$$\hat{A}_i^T = [0, \dots, 0, 1, 0, \dots, 0] \hat{A} = [0, \dots, 0, 1, 0, \dots, 0] \hat{U} \hat{W} \hat{V}^T \quad (5)$$

In a neural network interpretation, the input vector  $[0, \dots, 0, 1, \dots, 0]$  is a local representation for the  $i^{th}$  exemplar in the database. This exemplar is transformed into a hidden representation by multiplication by the matrix of weights  $\hat{U}\hat{W}$ . This results into a hidden representation of dimensionality  $p$ . This hidden representation is then multiplied times the orthonormal matrix  $\hat{V}^T$  to obtain a representation of dimensionality  $n$ . This representation should approximate the original dimensions of the  $i^{th}$  exemplar in the database. We can actually use the hidden layer representation as a concise representation of the exemplar.

## 3 SVD and eigen decompositions

Let  $X$  be an  $m \times n$  matrix of data, where  $m$  is the number of observations and  $n$  the number dimensionality of each observation. In computer vision problems typically  $m > n$ . The covariance matrix is  $C_x = \frac{X'X}{m}$ . The matrix of eigenvectors  $P$  is such that  $C_x = P\Lambda P^T$ , where  $\Lambda$  is diagonal and  $P$  is orthonormal. Now define

$$A = \frac{X'}{\sqrt{m}}$$

therefore  $C_x = AA'$ .

$A$  is an  $n \times m$  matrix and can be decomposed using singular value decomposition (SVD) in  $A = UWV^T$ . We can then rewrite  $C_x$  as:  $Cov = AA' = UWV^T VWU^T = UW^2U^T$ . Thus  $U$  columns of  $U$  are the eigenvectors of  $C_x$  and the squared singular values are the eigenvalues of  $C_x$ .

### 3.0.1 Shortcuts

Consider  $T = \frac{XX'}{m} = A'A$ , an  $m \times m$  matrix. In computer vision problems typically the number of images in the database is smaller than the number of pixels per image and thus it is preferable to work with  $T$  rather than  $C_n$ . If  $P$  is a matrix of eigenvectors of  $T$  then  $AP$  is an eigenvector of  $C_x$ . To see why note that  $e_i$  is an eigenvector of  $T$  iff  $Te_i = A'Ae_i = \lambda_i e_i$ . Thus  $AA'Ae_i = C_x(Ae_i) = \lambda_i(Ae_i)$  and  $(Ae_i)$  is an eigenvector of  $C_s$  with eigenvalue  $A\lambda_i$ .

If we are interested on getting only  $p$  eigenvectors (e.g., if we have more dimensions ( $m$ ) than samples ( $n$ ) we certainly do not want more than  $m$  eigenvectors) we can use an “economy” version of the SVD. There are routines that compute only the first  $p$  columns of  $U$  and therefore the first  $m$  rows of  $W$  giving  $U$  of size  $n \times p$ ,  $W$  of size  $p \times p$  and  $V$  of size  $p \times p$ . before.

These shortcuts avoid the multiplication needed to obtain  $C_x$  and the computation of all the columns of  $U$  and  $W$  we are not interested in.