Wireless Non-contact Cardiac and Neural Monitoring

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ABSTRACT
Ubiquitous physiological monitoring will be a key driving force in the upcoming wireless health revolution. Cardiac and brain signals in the form of ECG and EEG are two critical health indicators that directly benefit from long-term monitoring. Despite advancements in wireless technology and electronics miniaturization, however, the use of wireless home ECG/EEG monitoring is still limited by the inconvenience and discomfort of wet adhesive electrodes.

We have developed a wireless biopotential instrumentation system using non-contact capacitive electrodes that operate without skin contact. The sensors can be embedded within comfortable layers of fabric for unobtrusive use. All of the issues relating to the design of low noise, high performance capacitive sensors are discussed along with full technical details, circuit schematics and construction techniques.

The non-contact electrode has been integrated into both a wearable ECG chest harness as well a EEG headband. We have also designed a compact, battery-powered, wireless data acquisition system to interface with multiple electrodes and monitor patient cardiac and neural signals in real time. Experimental data shows that the non-contact capacitive electrode perform comparable to Ag/AgCl electrodes using our special chest harness and head bands to ensure tight, movement-free electrode positioning.

General Terms  
EEG, ECG, Wireless Health, Capacitive Sensors

1. INTRODUCTION
Brain and cardiac biopotential signals in the form of EEG and ECG are two critical physiological indicators that are directly suited for long-term wireless health monitoring. Yet despite advancements in wireless technology and electronics miniaturization, however, the use EEG/ECG has still been largely limited by the inconvenience and discomfort of conventional wet contact electrodes.

For home use, clinical grade adhesive electrodes are often cited as irritating and uncomfortable leading to low usage compliance. As an alternative, dry electrodes [1] [2] have started becoming much more common-place. However, like wet electrodes, dry electrodes still require direct electrical contact to the skin. In addition, dry electrodes, which do not have the benefit of a conductive gel, are much more sensitive to the condition of the skin and are highly susceptible to motion artifacts. For future wireless health systems, a less obtrusive sensor is needed to match the advancements made in wireless technology.

In contrast to wet and dry contact sensors, non-contact capacitive electrodes do not require an ohmic connection to the body. This offers numerous advantages since non-contact electrodes require zero preparation, are completely insensitive to skin conditions and can be embedded inside a garment for a completely unobtrusive, patient-friendly system. While the concept of non-contact biopotential sensors is not new, with the first working device reported decades ago [3], a practical device for patient use has yet to materialize. More recently, several authors have presented results from designs utilizing the latest in commercially available discrete low noise amplifiers [4] [5] [6], including some wireless designs [7].

Over the years, many clever designs have appeared, some proprietary. However, nothing has really progressed beyond the 'lab prototype' stage. In addition, general knowledge about capacitive sensors and how to design and construct them are scarce in literature. In this paper, we attempt to address these shortcomings by presenting the full designs,
including all the relevant details in the analog front-end, for a high-quality, contactless, wireless ECG/EEG monitor. In addition, we characterize the system-level performance by directly comparing the capacitive electrode against traditional, clinical Ag/AgCl electrodes and show that they perform equally well in many applications.

2. SYSTEM DESIGN
A full schematic depicting the wireless, non-contact sensor system is shown in Figure 1. Each capacitive electrode contains an onboard amplifier, filter, buffer and connects to the wireless base unit. The full operation of the capacitive electrode's amplifier and analog front-end, including circuit/noise theory, has been well described in previous publications [8] [9]. In this paper, we focus on the system-level design and results from our latest generation, optimized sensor.

Figure 1: Full schematic of wireless ECG/EEG system. The capacitive electrode PCB contains the front-end amplifier. Differential gain, digitization, active grounding and digital processing/wireless is contained on separate base unit.

Figure 2: Picture of the non-contact, capacitive electrode. The sensor is manufactured on a standard PCB, which contains the amplifier circuits on the top and the sensing plate on the bottom.

All of the electrodes, including the active ground, can be fully insulated. Since no galvanic connection is present and the device is battery powered, the system is very patient-friendly and safe to use.
Common problems associated with capacitive, non-contact electrodes include:

1. Noise - Capacitive electrodes exhibit a much larger intrinsic circuit noise floor.
2. Motion Artifacts - Even slight amounts of motion/friction saturate the signal.
3. Interference Pickup - Much greater sensitivity to 50/60Hz line noise.
4. Complexity - The need for exotic and expensive components directly on the electrode.

In general, these problems can be categorized as arising from two sources. The first consists of circuit design, accounting for the issues with complexity and intrinsic noise. The second is largely due to mechanical implementation and account for interference and motion artifacts. Through our experience, these problems with capacitive sensors are largely solved through modern components and careful design. The details will be explained in full throughout this paper.

We have developed a simple, repeatable, robust and relatively inexpensive method for producing high quality capacitive electrodes. The physical substrate of the electrode is a standard PCB. Figure 2 shows a close up of the latest generation of our non-contact electrodes. As before, amplifier circuits to buffer the weak signal acquired electrode are housed on the top. In the center, a snap connector is used to provide mechanical stability, as well as provide compatibility with standard medical/research instrumentation (additional power, reference and ground lines are needed as well).

The bottom plate of the electrode is a solid copper fill, which forms a parallel plate capacitor with the body to couple biopotential signals. In this version, the copper fill is not insulated with soldermask, allowing the sensor to optionally function as a dry contact electrode. As a dry-contact sensor, the signal is virtually indistinguishable from clinical wet Ag/AgCl electrodes. However, this paper will focus on the use of this sensor as a capacitive electrode, sensing signals through insulation such as fabric.

An active shield formed by the inner plane of the PCB and a ring around the sensing plate protects the electrode from external interference. The overall dimensions of the sensor is slightly larger than a US quarter.

In contrast to previous reported implementations [4] [5] which involved a combination of exotic components (such as the expensive, electrometer-grade INA116), capacitance cancellation schemes and proprietary/unpublished designs, we have built a very high quality active capacitive electrode based around a common, inexpensive and widely available amplifier, the National Semiconductor LMP7702. Only three resistors and three capacitors are required to complete the device.

The LMP7702 is a CMOS opamp in a dual SOIC-8 package with an input structure suitable for ultra-high impedance sensors. Although on paper, the current-noise is specified as ten times greater than the INA116, we have found the noise performance to be comparable, if not better in practice. In addition, the LMP7702 is specified to operate at a much lower supply voltage (down to 2.7V).

The first opamp in the package is configured as an unity-gain voltage buffer. The 10nF and 10k resistors are used to protect the input of the amplifier and isolate the output of the amplifier from the active shield. No external input biasing network is necessary with the LMP7702 and the inputs consistently charge and stay within the rail-to-rail input range during use. Likewise, the outputs are also stable since the amplifier has rail-to-rail outputs and is configured as unity gain. This achieves optimal performance since any bias network necessarily adds noise and degrades the input impedance.

The lack of a bias network, however, results in an undefined (although full usable) DC operating point. To remove this offset as well as low frequency noise/drift, a passive RC high pass filter with a corner frequency of 0.7Hz is used to center the signal around \( V_{ref} \). The second opamp in the package is then buffers this high-passed signal and drives the cable connecting the electrode to the base unit. A 100Ω resistor is used to isolate the cable capacitance from the amplifier’s output.

Although this lack of gain through multiple buffers is theoretically disadvantageous from a noise perspective, in practice the noise from the capacitive electrode to body interface will dominate the subsequent stages. Having a unity gain buffer also eliminates the need for precisely matched passive components at the electrode to achieve a good common-mode rejection ratio (CMRR).
2.2 Wireless Base Unit

Each of the electrodes outputs a buffered, unity-gain, analog signal. A compact, battery-powered base unit (Fig. 1) provides the necessary power, reference and ground lines.

An N-input differential amplifier was constructed by extending [10] the topology of the well known 3-input instrumentation amplifier. In general, any practical biopotential amplifier circuit should work well. Since the non-contact electrodes are AC coupled with low-offset buffers, it was possible to incorporate a large amount of gain (40dB) directly within one amplifier stage. A 16-bit ADC (AD7685) is used, resulting in a LSB of 0.5µV over an input range of 33mV.

A two pole passive RC filter is used to filter out high-frequency components before the ADC. Both corner frequencies are set at 159Hz. Although the anti-alias filter provides only a shallow roll-off, we use a sufficiently high sampling rate to avoid any noticeable aliasing artifacts. This also minimizes the number of passive and active components.

The overall bandwidth of the system is then dictated by the analog high-pass filter of the capacitive electrode, 0.7Hz, and the antialias filter, 159Hz.

2.3 Grounding

Subject grounding is one of the most important factors in achieving good signal quality. Unfortunately, it is often overlooked and not always explained clearly, despite its vital importance. In our experience, many of the problems with non-contact sensors were due to improper grounding.

In line with the idea of a fully insulated system, we use a capacitive coupling to connect the circuit ground back to the body. A dummy electrode without components is used to as the capacitive ground electrode. Such a ground is fully insulated, but offers only a weak coupling, rendering the system susceptible to interference. Actively driven grounding schemes are a well-known technique [11] to reduce common-mode interference and have been successfully adapted for capacitive sensors [12].

On the base unit, the common mode signal, \( V_{CM} \), is connected to an inverting amplifier with gain of -100 to provide an additional 40dB of CMRR for the system. The signal is fed back into the body through the dummy ground electrode.

An simple experiment, depicted in Figure. 3 illustrates the
effectiveness of this active ground. The capacitive active ground is as effective as a driven dry ground contact (anti-static wrist strap). Passive dry grounds start to suffer from 60Hz noise pick-up. A floating (purely parasitic) ground may also be used, but suffers from large 60Hz and other low frequency artifacts, and is not suitable for any serious measurements.

The combination of the active ground and the fact that the system is battery-powered, results in a very clean signal, free from 60Hz noise.

2.4 Data Acquisition

A simple 16-bit microcontroller (PIC24) was used to control the ADC. The base unit supports both Bluetooth wireless connectivity for live streaming of data to a PC or other display interface. For longer-term mobile recordings, a microSD interface is also available. The entire system is powered from a 900mA/hr rechargeable lithium-polymer battery good for approximately 10 hours of continuous recording.

The device is recharged through a mini-USB connector. A USB-RS232 converter (FT232R) is also available for higher bandwidth, real-time streaming of data than what is possible with the Bluetooth application. For safety reasons, this mode should only be used with an unplugged laptop, since no power isolation circuit is provided.

For the purposes of the experiments in this paper, we utilized the Bluetooth transmitter which streamed data into a simple PC display and logging application at a rate of 343Hz for the four signal channels.

For future, commercial-grade systems, it would be advantageous to use the latest in low-power wireless technology (ie. Bluetooth low-energy) as well as miniaturize the system’s form-factor.

3. WEARABLE SENSOR HARNESS

As mentioned earlier, capacitive electrodes do not have the benefit of being fixed to body. Consequently, they are very sensitive to motion errors and require a robust enclosure to achieve an optimal signal.

We have developed an ECG chest harness and an EEG headband (Fig. 4) to mount the non-contact electrodes. As shown later, a firm enclosure that fixes the electrodes to the body allows the non-contact electrode to perform almost as well as standard adhesive Ag/AgCl electrodes.

A compression vest was used as the basis of the ECG chest harness. Adaptation of the gynecomastia vest was prepared by sewing electrode snap connectors onto the vest and snapping the electrodes during use. Non-contact electrode placement was assigned to the two midaxillary positions. This vest was ideal for electrode placement due to its elastic con-
touring ability, covering of the thoracic surface with sufficient firmness. A second elastic band was also optionally available to add additional security for holding the electrodes in place.

For EEG experiments, a simple, tight, elastic cloth headband was used in a similar fashion by sewing in snap connectors for the non-contact electrodes. In contrast to known commercial and research headbands, our version allows for signals to be acquired through hair using the capacitive electrodes. The design and operation of the EEG headband was especially challenging due to the flexible properties of hair which make securing the electrodes difficult.

4. PHYSIOLOGICAL DATA
The ECG vest and EEG headband were used to collect live data using the capacitive sensors. For the purposes of generating a direct comparison, two of the four electrode inputs were connected to standard passive Ag/AgCl (3M Red Dot) and the other two were connected to the capacitive active electrodes. The subject was a healthy 21 year old male. Experiments were conducted in a standard electrical engineering lab with no effort to eliminate sources of interference.

4.1 ECG Experiments
For the ECG tests, the capacitive electrodes were mounted into the tight, body-fitting harness with the two capacitive electrodes on the left and right sides of the ribcage. The subject wore a simple cotton t-shirt underneath the harness. Two Ag/AgCl adhesive electrodes were also placed in a nearby position directly on the skin. The output signal for the capacitive sensor was defined by taking the difference between the two and likewise of the Ag/AgCl electrode pair.

Figure 5 shows a detailed plot of an ECG sample taken while the subject was sitting at rest. The overall signals are nearly indistinguishable in both shape and noise levels, even though the capacitive electrodes were operating through clothing. All relevant ECG features are clearly visible. The slightly smaller amplitude of the signal from the non-contact electrode is likely due to the signal attenuation from the extremely high source impedance.

One previous study [6] compared the performance of a proprietary capacitive electrode design versus contact electrodes with a subject lying down. We extend the methodology established in these tests to include data with an actively moving subject. Figure 7 shows 10-second plots comparing the signal acquired from the capacitive and Ag/AgCl electrodes.

As expected, the signal remains mostly undisturbed while the subject is at rest and walking lightly. During more vigorous activities, motion artifacts become problematic for both electrodes types, rendering the ECG signal useful for only R-R beat detection. The signal for the capacitive electrode is not substantially worse, as long as the capacitive electrodes are fixed tightly against the body using the harness. It should be worth noting, however, that capacitive electrodes are extremely sensitive to friction (rubbing against cotton), which necessitates the high chest harness.

We again used the same methodology as [6] to compare the extracted R-R beat intervals to show the equivalence of Ag/AgCl and capacitive electrodes, extending their study to subjects in motion. The plot is shown in Figure 6. The extracted R-R beat intervals are virtually identical across all the tested activities.

For applications beyond simple heart beat and rhythm detection, a clinical-grade multi-lead signal is required. We used the four input channels available from our device to construct an EASI [13] array to obtain a derived 12-lead ECG signal. The positioning and transformation coefficients were taken from [13]. Placement of electrodes at standard EASI positions and ground was accomplished by use of the adapted gynecomastia vest. Figure 8 shows the derived 12-lead ECG, which show the expected shape and features, such as the increasing amplitude of the R-wave progressing from the V1 to V6 lead.

4.2 EEG Experiments
Similar to the cardiac data, two of the input channels were connected to Ag/AgCl adhesive electrodes to achieve a direct comparison with the non-contact sensors. For the EEG experiments, one capacitive electrode was placed on the forehead (Fp1) and the second on the back (Oz), through hair. Likewise, an Ag/AgCl electrode was also placed on the forehead (Fp2). However, since it was not possible to place an contact electrode through hair, the second Ag/AgCl electrode was placed on the mandible (A1). Unless specified, the output for each electrode was defined as the signal at
Figure 9: Close-up of EEG signals acquired using a mix of Ag/AgCl (3M Red Dot) and capacitive non-contact electrodes. No extra filtering beyond the analog anti-alias has been applied to the raw signal to show that the sensor is free from 60Hz interference.

Figure 10: Experiment showing the signal from the frontal capacitive electrode (Fp1A1) in blue and the signal from the occipital capacitive electrode (O1A1). Eye blink artifacts are visible in the frontal electrodes during the first half of the recording. Strong alpha activity is seen in the occipital electrode after the subject’s eyes close.

each channel minus the common-mode of four channels.

Figure 9 shows a detailed time-domain plot of all four EEG channels with the subject relaxing, at rest with closed eyes. Not only are the expected alpha rhythms clearly visible (especially in the occipital electrode), the signals from the Ag/AgCl and capacitive electrodes are virtually identical. Strong alpha wave activity is seen, as expected for an awake, relaxed subject. The signals are all shown at full bandwidth, without an additional digital filtering showing the effectiveness of the active shield and driven ground.

A second montage consisting of two signals was obtained by using the A1 Ag/AgCl electrode as a reference for the frontal and parietal capacitive electrodes. In this experiment, the subject was asked to blink several times and then close his eyes. Figure 10 shows the clear blink artifacts in the Fp1A1 signal followed by the onset of alpha waves in the OzA1 signal.

The ability to easily obtain signals from the normally hair covered occipital and parietal regions is especially useful for brain-computer (BCI) and other EEG-based neural interfaces. Systems which can only obtain frontal EEG activity cannot obtain important responses including the P300 evoked potential and the steady-state visual evoked potentials (SSVP), commonly used in BCI applications.

To test the effectiveness of the capacitive electrode over the haired occipital region, a simple experiment where the subject was asked to watch a flashing LED was devised to measure the SSVP response.

Sleep diagnosis is an important medical application of EEG technology, and one that will directly benefit from having easy to use, unobtrusive, non-contact sensors. Home sleep
monitoring and coaching systems are already commercially available but rely on the limited set of signals available from forehead contact electrodes. The non-contact sensor allows for EEG signals to be acquired from the entire head, without gels.

A spectrogram depicting a period of sleep EEG taken from the O1 capacitive electrode is shown in Figure 11. The subject was asked to take a short nap. The different frequency components of sleep EEG activity are visible in the time-frequency plot.

5. CONCLUSION
We present the full designs for a wireless ECG/EEG monitoring system using insulated, non-contact sensors.

Non-contact sensors have traditionally been thought of as unsuitable for medical-grade applications, but we demonstrate how careful design, both at the circuit and system level can produce signals comparable to clinical grade Ag/AgCl electrodes for both ECG and EEG applications. The one area that is still currently unaddressed, however, is sensitivity to motion artifacts. Efforts directed at mitigating the non-contact electrode’s inherent sensitivity to motion/friction effects at the system and signal processing level is expected to yield large returns for this field.

This wireless and wearable system is ideally suited for future mobile health applications by being much more comfortable and patient-friendly than traditional contact based systems.

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7. REFERENCES


